RC10 B6 TEAM KIT

Driver: Jesper Rasmussen **Event:** EOS RD1

Date: **Track:** EOS RD1

Qualify: 9th **TQ:** ☐ **Main:** B **Finish:** 6th **Best Lap Time:**

Reset Forms

Front Suspension:

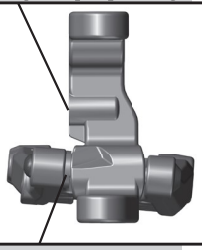
Ride Height:	16mm
Camber:	-1,5
Toe:	0
Arm Type:	Gullwings Hard
Tower Type:	Kit
Caster Block Insert:	+5
Bulkhead Type:	Brass
Kick-Up Angle:	25
Wheel Hex:	5mm

Notes:

Anti Roll Bar:
- None ☐
- White (0.8mm) ■
- Gray (0.9mm) ☐
- Blue (1.0mm) ☐
- Other: ☐

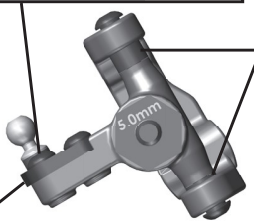
Steering Plate: kit

Steering Stop Spacing: 0mm



Caster Block Spacing: 1mm

Bump Steer Spacing: 0mm

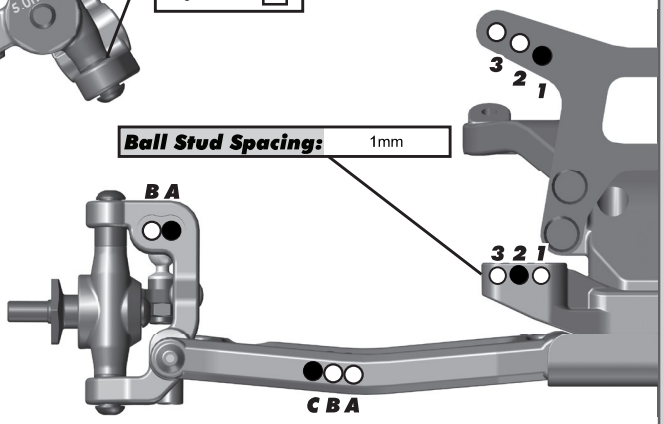


Axle Height:
- +3 ■
- +2 ☐
- +1 ☐
- 0 ☐

Ball Stud Spacing: 0mm



Ball Stud Spacing: 1mm



Rear Suspension:

Ride Height:	16mm
Camber:	-1,5
Wheel Hex:	6mm

Hub Spacing: Forward ☐ Middle ☐ Back ☐

Shock Mounting Position: Front of Arm ■ Rear of Arm ☐

Notes: Long wheel base

Anti Roll Bar:
- None ☐
- White (1.2mm) ■
- Gray (1.3mm) ☐
- Blue (1.4mm) ☐
- Other: ☐

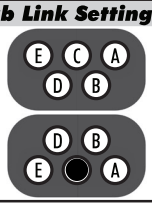
C Mount Inserts: 1° ■ 0.5° ☐



D Mount Inserts: 1° ☐ 0.5° ☐



Rear Hub Link Setting:



Hub Insert: +3 ■ +2 ☐ +1 ☐ 0 ☐

Ball Stud Spacing: 2mm

Electronics:

Radio:	sanwa	**Servo:**	reedy
EPA:	Throttle: %	Brake:	%
ESC:	reedy		
ESC Settings:			
Motor:	reedy		
Wind:	6.0	**Timing:**	20
Pinion:	22	**Spur:**	78
Battery:	reedy low profile		
Battery Position:			

Drivetrain:

Transmission:
- 3 Gear: ■ 4 Gear: ☐
- Stand Up: ☐ Lay Down: ■

Differential:
- Ball Diff: ☐ Gear Diff: ■

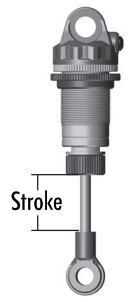
Notes: 2 small gear and 7000 oil

Slipper Clutch:

Type:	
# of Pads:	

Shocks:

	Front	Rear
Piston:	2x1.6	2x1.7
Fluid:	37.5	32.5
Spring:	Purple	blue
Limiters:	0	0
Stroke:	22.5	29.5
Eyelet Length:	long	short
Cup Offset:	+5	0
Notes:		



Track Info:

Size:	Small ☐	Medium ☐	Large ■	Extra Large ☐
Surface:	Dirt ☐	Carpet ■	Astroturf ☐	Multi Surface ☐
Traction:	Low ☐	Medium ☐	High ■	Very High ☐
Moisture:	Dry ☐	Damp ☐	Wet ☐	

Tires:

Front Tires:	
Front Compound:	
Front Insert:	
Rear Tires:	

Body, Wing, Weight:

Body:	JC
Wing:	JC
Wing Angle:	0° ☐ 3° ☐ 6° ■
Servo Weights:	